

GURU NANAK INSTITUTE OF TECHNOLOGY

An Autonomous Institute under MAKAUT

2020-2021

PROCESS CONTROL SYSTEM

EI(FT)701B

TIME ALLOTTED: 3 Hrs

FULL MARKS: 70

The figures in the margin indicate full marks.

Candidates are required to give their answers in their own words as far as practicable

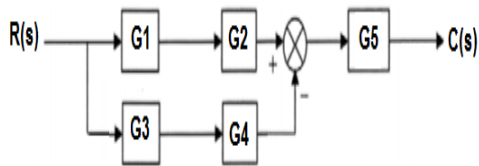
GROUP – A

(Multiple Choice Questions)

Answer any **ten** from the following, choosing the correct alternative of each question: **10×1=10**

		Marks	CO No
1(i)	Transfer function of a system is defined as a) Output/ Input b) Input/Output c) Laplace transform of Output/Laplace transform of Input when all initial conditions are zero d) Laplace transform of Input/Laplace transform Output of when all initial conditions are zero	1	CO1
(ii)	Which of the following controllers has maximum offset a) P controller b) PD controller c) PID controller d) I controller	1	CO2
(iii)	Tight shut off is not present in a) single seated valve b) double seated valve c) butterfly valve d) gate valve	1	CO4
(iv)	Reset rate is another term used for _____ time a) derivative b) integral c) dead d) none of these	1	CO2
(v)	What is the type of a system whose transfer function is $G(S) = 5/S^2(S^2 + 5S + 6)$ a) Type 0 ,Order 2 b) Type 2, Order 2 c) Type 2,Order 4 d) Type 1,Order 4	1	CO1
(vi)	Which controller cannot be used alone a) P controller b) I Controller c) D Controller d) All of these	1	CO2

- (vii) Stabilization time is minimum in 1 CO2
 a) I controller
 b) PD controller
 c) PID controller
 d) PI controller
- (viii) Find the total transfer function of the system. 1 CO1



- a) $(G1.G2 - G3.G4).G5$
 b) $(G1.G2 + G3) - G4.G5$
 c) $(G1 + G2).G3 + (G4 + G5)$
 d) $G1.G2 + G3.G4 - G5$
- (ix) V-port type valve is used for 1 CO4
 a) decreasing sensitivity
 b) increasing sensitivity
 c) linear sensitivity
 d) all the above
- (x) Bevelled disc type valve is used for 1 CO4
 a) decreasing sensitivity
 b) increasing sensitivity
 c) linear sensitivity
 d) all the above

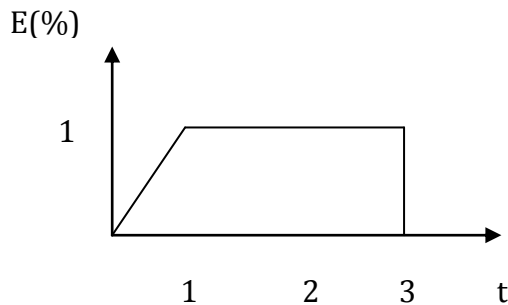
GROUP – B

(Short Answer Type Questions)

(Answer any *three* of the following)

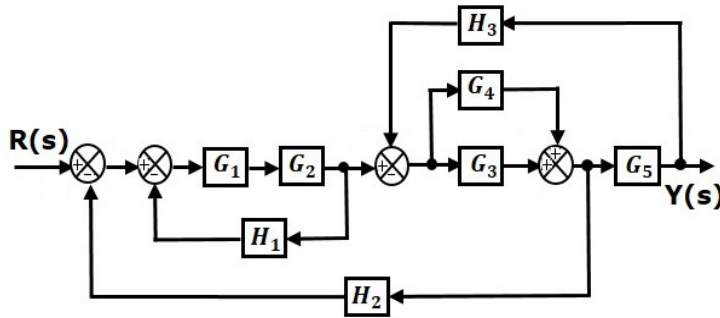
3 x 5 = 15
Marks CO No
 5 CO2

2. Plot the graph of a PI controller output as a function time. The error to the controller is shown in fig. $K_p=5$, $K_I=1.0 \text{ s}^{-1}$, $PI(0)=20\%$.



3. Plot the graph of a PI controller output as a function time. The error to the controller is shown in fig. $K_p=5$, $K_I=1.0 \text{ s}^{-1}$, $PI(0)=20\%$. 5 CO2

4. Find the overall Transfer of the system. 5 CO1



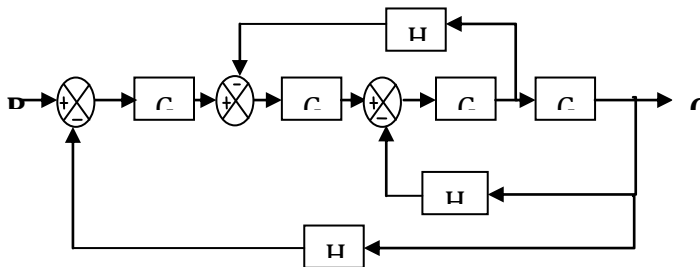
5. “Actuator power required for a single seated valve is greater than the double seated valve”. Justify the statement with proper diagram. 5 CO4
6. Design an electronic integral controller of input range 6V, an output of 5V and KI of 3.0%/%-min 5 CO 2

GROUP – C

(Long Answer Type Questions)
(Answer any *three* of the following)

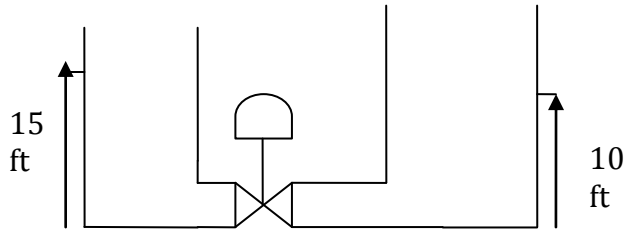
3 x 15 = 45
Marks CO No

- 7.a) What are the operational aspects of instrument system? 5 CO1
- 7.b) Find out the overall transfer function of the system using block diagram reduction algebra 7 CO1



- 7.c) For the transfer function given below find out 3 CO1
 i) poles & zeros of the system
 ii) order & type of the system
 $G(S) = (S^2 + 1) / (S(S^2 + 3S + 2)(S+6))$
8. a) A water tank is gradually losing heat and its temperature drops by 2°K per minute. When the heater is on, the system gains temperature at 4° K per minute. A two position controller has a .5 minute control lag and a neutral zone of ±4% about a set point of 323° K. Plot the temperature versus time graph and find the oscillation period. Assume at t=0, temperature is at set point and the heater is off 7 CO2
8. b) What is rangeability? Explain the cavitation and flashing phenomena with the help of a diagram. 5 CO4

8. c) Calculate C_v & K_v of the valve for the system shown in figure which regulates the flow of glycerine. Specific gravity of glycerine is 1.4. 3 CO4



9. a) What is a Feed forward system, explain briefly. What are the advantages and disadvantages of the system? 5 CO3
9. b) What is Cascade Control? Explain with example. 5 CO3
9. c) Explain one Scheme of Ratio Control & its application. 5 CO3
- 10.a) Why valve- positioner is required with an actuator? Explain the operating principle of a valve positioner. 7 CO4
10. b) What is valve sizing? Define C_v and K_v . 5 CO4
- 10.c) A valve with a C_v rating of 4.0 is used to throttle the flow of glycerine for which specific gravity relative to error (G) is 1.26. Determine the maximum flow through the valve. 3 CO4
11. Write short notes on any three: 3x5
- 11.a) Spring actuator with positioner 5 CO4
- 11.b) Ratio Control 5 CO3
- 11.c) Feedforward control 5 CO3
- 11.d) Solenoid as actuator 5 CO4
- 11.e) Safety valve 5 CO4